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# **Application Pre-Approval / Installation Form**

General Information Application Completion Date:	3DLevelScanner Model: S M MV MVL2	
Company Name:		
Street:	City:	
Zip:	State:	
Contact Name:	Title:	
Phone:	Fax:	
E-mail:	Representative:	

## **1. Application Details**

1	Quantity of vessels to be mo	nitored				
2	Potential number of vessels to be monitored					
3	Material					
4	Industry		Select Fre	om List:, O	ther:	
5	Material Density		, 🗌 g/cc, 🗌 lbs/Cu. ft.			
6	Max Pressure		, [	] Bar, 🗌	PSI	
7	Max Temperature inside the	vessel , Fahrenheit, Celsius				
8	Vessel Shape	Select From List:, Other:				
9	Rectangular	Length:	Width: Height:		Height:	🗌 m
10	Round	Diameter:	Height:			🗌 ft
11	Internal Structure	Select From List:, Other:				
12	Internal Movement	No Yes please describe				
13	Material Maximum Level	, 🗌 m, 🗌 ft				
14	Explosive area	YES, NO If yes, please designate classification:				
15	24vDC Power available	YES,NO				
16	Outputs required	4-20mARS-485				
17	Outputs used for	Inventory Control				
18	Previous technology used:					

### Blueprints of vessel's shape and expected possible mounting locations are required.

### Approved by:

Title:

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Full Name:

Signature:



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### **Company Name:**

### **2.** Material Characteristics

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Angle of Rep	oose:			
Particle Type	e: Select from list	Characteristics: Select From List		
3. Vessel	Details			
Vessel Shape	e: Select from list	Internal Structure: Select from list, Other:		
Note: It is re	commended to put the Empty calibration	level above internal structure		
4. Vessel	Dimensions (internal)			
Center	CYLINDER: Height: Diameter:			
	Тор	Bottom		
Flat Cone: He Dome: H Pyramid: Other:	eight:	Flat Cone: Height: Bottom Diameter: Dome: Height: Pyramid: Height: X: Y: Other:		
Top-Dome Top-Dome Top-Cone Bottom - Dome Top - Cone Top - Con				
5. Filling	and Emptying Processes			
Filling Metho	od: Gravity Pneumatic Conveyor	Other: Dust during fill: YES, NO		
Emptying Mo	ethod: 🔲 Gravity 🗌 Pneumatic 🗌 Convey	vor Other:		

Note: When using air pressure inside the vessel near the emptying location, the bulk density might change and effect the measurements

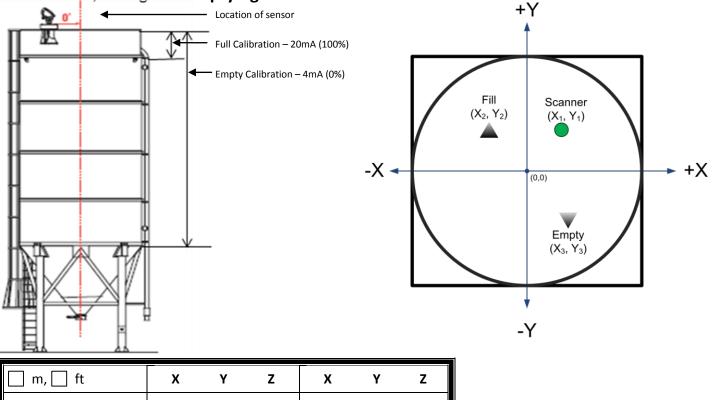
Max Filling Rate: Tons/hr	Total Capacity when vessel is full: Tons
Max Emptying Rate: Tons/hr	Weight below Empty Calibration level: Ton



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#### 150 Venture Boulevard · Spartanburg, SC 29306 Tel: (800) 778-9242 · (864) 574-8060 Fax: (864) 574-8063 E-mail: <u>sales@bindicator.com</u>

### 6. Scanner, Filling and Emptying Locations



m, ft	Х	Y	Z	Х	Y	Z
Scanner Location :		, ,			· ,	
Filling Location:		, ,			· ,	
Emptying Location:		, ,			· ,	
Full Calibration	,	🗌 m, [	ft			
Empty Calibration	,	🗌 m, [	ft			

Note: Scanner's Z position is measured from the bottom of the vessel

Note: Full/Empty Calibration Distances measured from scanner's transducers top

### 7. Electrical Power requirements & Signal Outputs

Power Supply Requirement	2 Wires – for 24VDC (range 20 to 36VDC)
Steedend Outputs	2 wires – for 4-20mA and HART Communications
Standard Outputs	2 wires – for RS485 (Twisted-Pair, 120 Ohm Impedance, Shielded)

### Approved by:

Full Name:	 Title:	
Date:	 Signature:	

### Note:



Cells enclosed with the sample on the left must be filled prior to the configuration of the 3DLevelScanner.